

GROVE CITY COUNCIL
SPECIAL MEETING
THURSDAY, JANUARY 21, 2016
6:30 PM
ROOM 6 – GROVE COMMUNITY CENTER
104 WEST THIRD STREET - GROVE, OK 74344

The Grove City Council met in special session on Thursday, January 21, 2016 at 6:30 PM with Mayor, Marty Follis presiding. Members present were Ed Trumbull, Don Nielsen, Marty Dyer and Ivan Devitt. Also present was City Manager, Bill Keefer; City Attorney, Darren Cook; Assistant City Manager, Debbie Bottoroff; Public Works Director, Jack Bower and City Clerk, Bonnie Buzzard. City Treasurer, Lisa Allred was absent.

At 6:31 PM Devitt made the motion for the Council to adjourn and reconvene in Room 5 – Grove Community Center. Seconded by Nielsen. AYE: Trumbull, Nielsen, Dyer, Devitt and Follis. NAY: None. Motion carried.

Follis opened the floor for discussion with respect to presentation from Poe & Associates on the Adopted Pavement Management Plan. Vice-President, Jim Hemphill of Poe & Associates addressed the Council to detail on the project approach of the Pavement Management Plan. Hemphill detailed on the following topic of discussion:

- Background, Data Collection and Data Update
- Micro-Paver Methodology & Micro-Paver & ICON
- Goals of Pavement Management Systems
- Network Definition
- Branches and Sections
- Pavement Condition Survey
- Typical Distresses
- Drainage Survey
- GIS Maps
- Pavement Life Cycle
- Performance Curves
- Project Results
- Current Funding Scenario
- Level PCI Funding Scenario

Hemphill added that timely routine repairs such as patching and crack sealing will slow the deterioration of both asphalt and concrete pavements and should be included in the program. Hemphill entertained questions, comments and concerns from the Council and Staff, and the following individuals:

- Dave Helms
- Jack Smith, and
- Sheila Stogsdill

Hemphill's presentation lasted for approximately 50 minutes. No formal action was taken from the Council.

At 7:27 PM Devitt made the motion to adjourn. Seconded by Nielsen. AYE: Trumbull, Nielsen, Dyer, Devitt and Follis. NAY: None. Motion carried.